Control and Learning for a Bipedal Robot

**Part 1:** Design controller for walking (1 or 2 from literature)

**Part 2:** Learn to walk (using ML)

Inter-disciplinary project:
- Roberto Calandra (Informatik - IAS)
- Philipp Beckerle (Maschinenbau - IMS)
- Sasha Voloshina (Sport Science - LaufLabor)

At the end: Publish a paper in an international conference

For more information contact Roberto at: calandra@ias.tu-darmstadt.de